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$D(q^{-1})A(q^{-1})[T(t)(\tau + 1)](3.161)$ and the parameter adaptation algorithm satisfying the passivity condition will take the form: $\tau(t+1) = \tau(t) + P(t)(y(t) - \hat{y}(t)) / (3.162)$ The equivalent feedback representation associated with the output error predictor using the above PAA is shown in Fig. 3.9.

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